NAVIGATION 04/26/2024

DVL500-Compact - 300 m





Tracking du fond de 0.3 à 175 m. Opérationnel jusqu'à 300 m

The DVL500-Compact combines the compact design of the standard DVL1000 with the superior bottom-track range of the DVL500. It can fly higher in the water column and closer to the seabed than similar equipment, enabling small vehicles to do bigger jobs.

Highlights

- ✓ Bottom-track from 0.3-175 m range
- Per-ping and per-beam data quality estimates
- ✓ 300 m operational depth

Applications

- ✓ Small vehicles requiring longer bottom track range
- Compact AUVs with high accuracy requirements
- ✓ Easy integration with leading inertial navigation systems (INS)

Technical specifications

| → Bottom velocity | |
|---------------------------|--|
| Single ping std @ 1.5 m/s | 0.8 cm/s at 1/2 max altitude |
| Long-term accuracy | ±0.1% / ±0.1 cm/s |
| Minimum altitude | 0.1 m |
| Maximum altitude | 175 m |
| Velocity resolution | 0.01 mm/s |
| Maximum ping rate | 8 Hz max |
| → Water tracking | |
| Minimum accuracy | 0.3% of measured value ± 0.3 cm/s |
| Minimum range | 4.0 m |
| → Current profiling | |
| Minimum accuracy | 0.3% of measured value ± 0.3 cm/s |
| Velocity resolution | 0.1 cm/s |
| Interval | User-specified Nth ping |
| Maximum range | 70 m |
| Blanking | 0.5 m |
| Cell size | 0.5-4.0 m |
| Max # cells | 140 |
| → Environmental | |
| Operating temperature | -4 to +40 °C |
| Storage temperature | -20 to +60 °C |
| Vibration | IEC60068-2-64 |
| EMC approval | IEC/EN 61000-6-2, 61000-6-3 |
| → Mechanical | |
| Depth rating | 300 m |
| Weight | 1.7 kg |
| Weight in water | 0.3 kg |
| Height | 158 mm |
| Diameter | ø 114 mm |
| → Hardware | |
| Frequency of operation | 500 kHz |
| Beam width | 5.8° |
| Configuration | 4-beam Janus array convex transducer, 25° beam angle |
| Internal memory | 16 GB / 64 GB optional |
| Frequency of operation | 500 kHz |
| Bandwidth | 25% centered at transmit frequency |
| → Interfaces | |

| Serial (either serial or Ethernet) | Configurable RS232 or RS422 SubConn connector, 8-pin male | |
|---|---|--|
| Ethernet | 10/100 Mbits Auto MDI-X. TCP/IP, UDP/IP, HTTP protocols. Fixed IP / DHCP client / Auto IP address assignment. UPnP and Nortek proprietary instrument discovery over Ethernet. IEEE1588/PTP and NTP for absolute time stamping. Multiple simultaneous data format transmission possible. | |
| Data formats | Nortek proprietary w/ $1\ \text{ms}$ timestamp accuracy, NMEA0183, variants of PDx | |
| Trigger | Internal 1, 2, 3, 4, 5, 6, 7 or 8 Hz or Trigger In. Trigger option through command (Ethernet or serial). External TTL or 485 lines: (configurable Rising/Falling/Edges) | |
| → Sensors | | |
| Pressure | 0.1% FS /precision better than 0.002% of full scale per sample | |
| Temperature | -4° to +40 °C ± 0.1 °C | |
| → Power | | |
| DC input | 12-48 V | |
| Maximum continuous current | 1.5 A | |
| Average power | 3.0 W* | |
| Power based on 1 Hz sampling and altitude with greatest transmit pulse. | | |
| → Materials | | |

POM housing

Standard models