



DVL 500 Compact

300 m, Generation 3

Bottom-track from 0.1 to 175 m range; 300 m operational depth



The DVL 500 Compact combines the compact design of the standard DVL 1000 with the superior bottom-track range of the DVL 500. It can fly higher in the water column and closer to the seabed than similar equipment, enabling small vehicles to do bigger jobs.

Download our guide to Nortek DVLs [here](#).

Highlights

- ✓ Bottom-track from 0.1-175 m range
- ✓ Per-ping and per-beam data quality estimates
- ✓ 300 m operational depth

Applications

- ✓ Small vehicles requiring longer bottom track range
- ✓ Compact AUVs with high accuracy requirements
- ✓ Easy integration with leading inertial navigation systems (INS)

Technical specifications

Bottom velocity

| | |
|---------------------------|---|
| Single ping std @ 1.5 m/s | 0.8 cm/s at 1/2 max altitude |
| Long-term accuracy | $\pm 0.1\%$ / ± 0.1 cm/s (export-controlled), $>1\%$ (license-free) |
| Minimum altitude | 0.1 m |
| Maximum altitude | 175 m |
| Velocity resolution | 0.01 mm/s |
| Maximum ping rate | 8 Hz max |

Water tracking

| | |
|------------------|---------------------------------------|
| Minimum accuracy | 0.3% of measured value ± 0.3 cm/s |
| Minimum range | 4.0 m |

Current profiling

| | |
|---------------------|---------------------------------------|
| Minimum accuracy | 0.3% of measured value ± 0.3 cm/s |
| Velocity resolution | 0.1 cm/s |
| Interval | User-specified Nth ping |
| Maximum range* | 70 m |
| Blanking | 0.5 m |

Current profiling

| | |
|-------------|-----------|
| Cell size | 0.5-4.0 m |
| Max # cells | 140 |

*Dependent on measurement conditions

Environmental

| | |
|-----------------------|-----------------------------|
| Operating temperature | -4 to +40 °C |
| Storage temperature | -20 to +60 °C |
| Vibration | IEC60068-2-64 |
| EMC approval | IEC/EN 61000-6-2, 61000-6-3 |

Mechanical

| | |
|-----------------|----------|
| Depth rating | 300 m |
| Weight | 1.7 kg |
| Weight in water | 0.3 kg |
| Height | 158 mm |
| Diameter | ø 114 mm |

Hardware

| | |
|------------------------|--|
| Frequency of operation | 500 kHz |
| Beam width | 5.8° |
| Configuration | 4-beam Janus array convex transducer, 25° beam angle |
| Internal memory | 16 GB / 64 GB optional |
| Frequency of operation | 500 kHz |
| Bandwidth | 25% centered at transmit frequency |

Interfaces

| | |
|------------------------------------|--|
| Serial (either serial or Ethernet) | Configurable RS232 or RS422 SubConn connector, 8-pin male |
| Ethernet | 10/100 Mbps Auto MDI-X. TCP/IP, UDP/IP, HTTP protocols. Fixed IP / DHCP client / Auto IP address assignment. UPnP and Nortek proprietary instrument discovery over Ethernet. IEEE1588/PTP and NTP for absolute time stamping. Multiple simultaneous data format transmission possible. |
| Data formats | Nortek proprietary w/ 1 ms timestamp accuracy, NMEA0183, variants of PDx |
| Trigger | Internal 1, 2, 3, 4, 5, 6, 7 or 8 Hz or Trigger In. Trigger option through command (Ethernet or serial). External TTL or 485 lines: (configurable Rising/Falling/Edges) |

Sensors

| | |
|-------------|--|
| Pressure | 0.1% FS /precision better than 0.002% of full scale per sample |
| Temperature | -4° to +40 °C ± 0.1 °C |

Power

| | |
|----------------------------|---------|
| DC input | 12-48 V |
| Maximum continuous current | 1.5 A |
| Average power | 3.0 W* |

* Power based on 1 Hz sampling and altitude with greatest transmit pulse.

Materials

Standard models

POM housing