

DVL 500 Compact, Schilling

6000 m

Bottom-track from 0.1 to 175 m range; 6000 m operational depth, Seanet connector.



This special version of the DVL 500 Compact comes fitted with a Seanet connector, allowing for seamless integration with TechnipFMC's Schilling Robotics work-class ROVs. Nortek has worked closely with TechnipFMC Schilling Robotics to extensively test and integrate this DVL with their ROVs, enabling users to enjoy extended range in a compact package.

The DVL 500 Compact combines the compact design of the standard DVL 1000 with the superior bottom-track range of the DVL 500.

Download our guide to Nortek DVLs here.

Highlights

- Specially equipped with Seanet connector for TechnipFMC's Schilling Robotics ROVs
- ✓ Bottom-track from 0.1 to 175 m range
- ✓ Per-ping and per-beam data quality estimates

Applications

- ✓ Navigation and control for TechnipFMC Schilling Robotics work-class ROVs
- Drop-in replacement for existing DVLs with little configuration effort

Technical specifications

Bottom velocity	
Single ping std @ 1.5 m/s	0.8 cm/s at 1/2 max altitude
Long-term accuracy	$\pm 0.1\%$ / ± 0.1 cm/s (export-controlled), >1% (license-free)
Minimum altitude	0.1 m
Maximum altitude	175 m
Velocity resolution	0.01 mm/s
Maximum ping rate	8 Hz max
Water tracking	

Water tracking	
Minimum accuracy	0.3% of measured value $\pm~0.3$ cm/s
Minimum range	4.0 m

Current profiling	
Minimum accuracy	0.3% of measured value $\pm~0.3$ cm/s
Velocity resolution	0.1 cm/s

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Current profiling					
Interval	User-specified Nth ping				
Maximum range*	70 m				
Blanking	0.5 m				
Cell size	0.5-4.0 m				
Max # cells	140				
*Dependent on measurement conditions					
Environmental					
Operating temperature	-4 to +40 °C				
Storage temperature	-20 to +60 °C				
Vibration	IEC60068-2-64				
EMC approval	IEC/EN 61000-6-2, 61000-6-3				
Mechanical					
Depth rating	6000 m				
Weight	5 kg				
Weight in water	3.1 kg				
Height	217 mm				
Diameter	ø124 mm with connector				
Hardware					
Frequency of operation	500 kHz				
Beam width	5.8°				
Configuration	4-beam Janus array convex transducer, 25° beam angle				
Internal memory	16 GB / 64 GB optional				
Bandwidth	25% centered at transmit frequency				
Interfaces					
Serial (either serial or Ethernet)	Configurable RS232 or RS422, Seanet connector				
Ethernet	10/100 Mbits Auto MDI-X.TCP/IP, UDP/IP, HTTP protocols. Fixed IP / DHCP client /Auto IP address assignment. UPnP and Nortek proprietary instrument discovery over Ethernet. EEE1588/PTP and NTP for absolute time stamping. Multiple simultaneous data format transmission possible.				
Data formats	Nortek proprietary w/ 1 ms time stamp accuracy, NMEA0183, variants of PDx				
Trigger	Internal 1, 2, 3, 4, 5, 6, 7 or 8 Hz or Trigger In. Trigger option through command (Ethernet or serial) External TTL or 485 lines: (configurable Rising/Falling/Edges)				
Sensors					
Pressure	0.1% FS /precision better than 0.002% of full scale per sample				
Temperature	-4° to 40 °C ± 0.1 °C				
Power					
DC input	12-48 V				
Maximum continuous current	1.5 A				

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Average power

3.0 W*

Materials

Materials

POM and titanium housing

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^{*} Power based on 1 Hz sampling and altitude with greatest transmit pulse.